# Polynomial Optimzation in Quantum Information Theory

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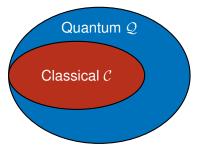
University of Konstanz

ICERM - 2018 Real Algebraic Geometry and Optimization



# Warm Up

- Entanglement is one of the key features in Quantum Information
- Bell '64:



- How to distinguish C and Q?
- What is the correct definition for Q? Does it matter?
- Can Polynomial Optimization help to understand these sets?

#### **Polynomial Optimization**

- $f \in \mathbb{R}[X]$  polynomial in commuting variables
- $g_0 = 1, g_1, \dots, g_r \in \mathbb{R}[\underline{X}]$  defining a semi-algebraic set:

$$K = \{\underline{a} \in \mathbb{R}^n \mid g_0(\underline{a}) \ge 0, \dots, g_r(\underline{a}) \ge 0\}$$

Want to minimize f over K

$$\begin{array}{ll} f_* = \inf f(\underline{a}) & \text{ s.t. } \underline{a} \in K \\ = \sup a \in \mathbb{R} & \text{ s.t. } f - a \geq 0 \text{ on } K \end{array}$$

NP-hard

RAG helps

$$f_* = \sup a \in \mathbb{R}$$
 s.t.  $f - a \ge 0$  on  $K$ 



• 
$$M(g) := \{ p = \sum_j h_j^2 g_{i_j} \text{ for some } h_i \in \mathbb{R}[\underline{X}] \}$$

sos relaxation

$$f_{sos} = \sup a \in \mathbb{R}$$
 s.t.  $f - a \in M(g)$  "SDP"  $\odot$ 

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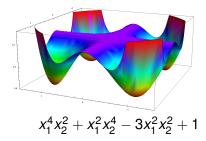


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- *f<sub>sos</sub>* is always a lower bound but might be strict
- If M(g) is archimedean:
   f<sub>\*</sub> = f<sub>sos</sub>



SOS hierarchy

• 
$$M(g)_t := \{ p = \sum_j h_j^2 g_{i_j} \text{ for some } h_i \in \mathbb{R}[\underline{X}]_t \}$$

sos hierarchy

$$f_t = \sup a \in \mathbb{R} \quad \text{s.t.} \ f - a \in M(g)_t \quad \text{SDP} \odot$$

#### We have

- $f_t \leq f_{t+1} \leq f_*$
- $f_t$  converges to  $f_{sos}$  as  $t \to \infty$
- If M(g) is archimedean:  $f_{sos} = f_*$

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  - $f_t$  converges to  $f_{sos}$  as  $t \to \infty$
  - If M(g) is archimedean:  $f_{sos} = f_*$
- Certificate of exactness:
  - Flatness of dual solution
  - Allows extraction of optimizers

#### **NC** Polynomials

- Want to replace scalar variables by matrices/operators
- Free algebra  $\mathbb{R}\langle \underline{X} \rangle$  with noncommuting variables  $X_1, \ldots, X_n$
- Polynomial

$$f=\sum_{w}f_{w}w$$

• Let 
$$\underline{A} \in (\mathcal{S}^d)^n$$
:  $f(\underline{A}) = f_1 I_d + f_{X_1} A_1 + f_{X_2 X_1} A_2 A_1 \dots$ 

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- Let  $\underline{A} \in (S^d)^n$ :  $f(\underline{A}) = f_1 I_d + f_{X_1} A_1 + f_{X_2 X_1} A_2 A_1 \dots$
- Add involution \* on  $\mathbb{R}\langle \underline{X} \rangle$ 
  - fixes  $\mathbb{R}$  and  $\{X_1, \ldots, X_n\}$  pointwise

$$X_i^* = X_i$$

Consequence

$$f^*f(\underline{A}) = f(\underline{A})^T f(\underline{A}) \succeq 0$$

NC Polynomial Optimization

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#### Eigenvalue optimization

• Let  $f \in \mathbb{R}\langle \underline{X} \rangle$ 

 $f_{nc} = \sup a \in \mathbb{R}$  s.t.  $f - a \succeq 0$  on K



► Observation: Checking if f = ∑<sub>i</sub> h<sub>i</sub><sup>\*</sup> h<sub>i</sub> is an SDP so as well checking f = ∑<sub>j</sub> h<sub>j</sub><sup>\*</sup> g<sub>ij</sub> h<sub>j</sub> (with degree bounds)

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- sos relaxation

$$M_{\mathit{nc}}(g) := \{ p = \sum_j h_j^* g_{i_j} h_j ext{ for some } h_i \in \mathbb{R} \langle \underline{X} 
angle \}$$

$$f_{sos} = \sup a \in \mathbb{R}$$
 s.t.  $f - a \in M_{nc}(g)$ 

- Fact:  $f_{sos} \leq f_{nc}$
- Theorem (Helton et al.): If  $M_{nc}(g)$  is archimedean, then  $f_{sos} = f_{nc}$ .

#### Eigenvalue optimization

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$$M_{nc}(g)_t := \{ p = \sum_j h_j^* g_{i_j} h_j \text{ for some } h_j \in \mathbb{R} \langle \underline{X} \rangle_t \}$$

sos hierarchy

 $f_t = \sup a \in \mathbb{R}$  s.t.  $f - a \in M_{nc}(g)_t$  SDP  $\odot$ 

•  $f_t \leq f_{t+1} \leq f_{nc}$  but inequalities might be strict

- $f_t$  converges to  $f_{sos}$  as  $t \to \infty$
- ▶ If  $M_{nc}(g)$  is archimedean:  $f_{sos} = f_{nc}$  and hence  $f_t \to f_{nc}$  as  $t \to \infty$

Trace optimization

• Let 
$$f \in \mathbb{R}\langle \underline{X} \rangle$$

$$f_{tr} = \sup a \in \mathbb{R}$$
 s.t.  $Tr(f - a) \ge 0$  on  $K$ 

K contains only operators, for which a trace is defined

#### Trace optimization

• Let  $f \in \mathbb{R}\langle \underline{X} \rangle$ 

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NP-hard 😣 J

K contains only operators, for which a trace is defined

If f = ∑<sub>j</sub> h<sub>j</sub><sup>\*</sup>g<sub>ij</sub>h<sub>j</sub> + ∑<sub>k</sub>[p<sub>k</sub>, q<sub>k</sub>] then Tr(f(A)) ≥ 0 for all A ∈ K
 sos relaxation

 $M_{tr}(g) := \{\sum_{j} h_{j}^{*} g_{i_{j}} h_{j} \text{ for some } h_{i} \in \mathbb{R}\langle \underline{X} \rangle \} + [\mathbb{R}\langle \underline{X} \rangle, \mathbb{R}\langle \underline{X} \rangle]$ 

$$f_{sos} = \sup a \in \mathbb{R}$$
 s.t.  $f - a \in M_{tr}(g)$ 

Fact:  $f_{sos} \leq f_{tr}$ 

▶ Theorem (B.,Klep et al.): If  $M_{tr}(g)$  is archimedean, then  $f_{sos} = f_{tr}$ .

#### Trace optimization

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•  $M_{tr}(g)_t := \{\sum_j h_j^* g_{i_j} h_j \text{ for some } h_j \in \mathbb{R}\langle \underline{X} \rangle_t\} + \sum [\mathbb{R}\langle \underline{X} \rangle, \mathbb{R}\langle \underline{X} \rangle]$ 

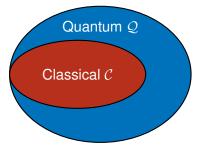
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# Back to Quantum Information

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# Basics of quantum theory

- ► A quantum system corresponds to a Hilbert space *H*
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- $\psi$  is entangled if it is not a product state

 $\psi_A \otimes \psi_B$  with  $\psi_A \in \mathcal{H}_A, \psi_B \in \mathcal{H}_B$ 

## Basics of quantum theory

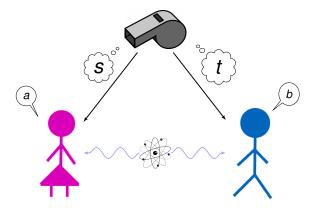
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 $\psi_{A} \otimes \psi_{B}$  with  $\psi_{A} \in \mathcal{H}_{A}, \psi_{B} \in \mathcal{H}_{B}$ 

- A state  $\psi \in \mathcal{H}$  can be measured
  - ▶ outcomes a ∈ A
  - ▶ POVM: a family  $\{E_a\}_{a \in A} \subseteq B(\mathcal{H})$  with  $E_a \succeq 0$  and  $\sum_{a \in A} E_a = 1$
  - probablity of getting outcome *a* is  $p(a) = \psi^T E_a \psi$ .

### Nonlocal bipartite correlations

- Question sets S, T, Answer sets A, B
- No (classical) communication



• Which correlations p(a, b | s, t) are possible?

### Correlations

#### Classical strategy ${\mathcal C}$

Independent probability distributions  $\{p_s^a\}_a$  and  $\{p_t^b\}_b$ :

$$p(a,b \mid s,t) = p_s^a \cdot p_t^b$$

shared randomness: allow convex combinations

## Correlations

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#### Quantum strategy $\mathcal{Q}$

POVMs  $\{E_s^a\}_a$  and  $\{F_t^b\}_b$  on Hilbert spaces  $\mathcal{H}_A, \mathcal{H}_B, \psi \in \mathcal{H}_A \otimes \mathcal{H}_B$ :

$$p(a,b \mid s,t) = \psi^{T}(E_{s}^{a} \otimes F_{t}^{b})\psi$$

- ► Nonlocality:  $(E_s^a \otimes 1)(1 \otimes F_t^b) = (1 \otimes F_t^b)(E_s^a \otimes 1)$
- If  $\psi = \psi_A \otimes \psi_B$  then we have classical correlation

### More correlations

#### Quantum strategy ${\cal Q}$

POVMs  $\{E_s^a\}_a$  and  $\{F_t^b\}_b$  on Hilbert spaces  $\mathcal{H}_A, \mathcal{H}_B, \psi \in \mathcal{H}_A \otimes \mathcal{H}_B$ :

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Quantum strategy  $Q_c$ 

POVMs  $\{E_s^a\}_a$  and  $\{F_t^b\}_b$  on a joint Hilbert space, but  $[E_x^a, F_y^b] = 0$ :

$$p(a, b \mid s, t) = \psi^{T} (E_{s}^{a} \cdot F_{t}^{b}) \psi$$

Fact

$$\mathcal{C}\subseteq \mathcal{Q}\subseteq \overline{\mathcal{Q}}\subseteq \mathcal{Q}_{\textbf{C}}$$

# Tsirelson's problem

#### Fact

#### $\mathcal{C}\subseteq\mathcal{Q}\subseteq\overline{\mathcal{Q}}\subseteq\mathcal{Q}_{\textbf{C}}$

- Bell:  $C \neq Q$
- ▶ closure conjecture [Slofstra '16]:  $Q \neq \overline{Q}$
- weak Tsirelson [Slofstra '16]:  $Q \neq Q_c$
- Dykema et al. '17: Concrete example in a decent subset of Q
- strong Tsirelson (open): Is  $\overline{Q} = Q_c$ ?
- strong Tsirelson is equivalent to Connes embedding problem

### Nonlocal games

- Characterized by
  - > 2 sets of questions S, T, asked with probability distribution  $\pi$
  - 2 sets of answers A, B
  - A winning predicate  $V : A \times B \times S \times T \rightarrow \{0, 1\}$

#### Nonlocal games

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Winning probability (value of the game)

$$\omega = \sup_{p} \sum_{s \in S, t \in T} \pi(s, t) \sum_{a \in A, b \in B} V(a, b; s, t) p(a, b | s, t)$$
$$= \sup_{p} \sum_{a, b, s, t} f_{abst} p(a, b | s, t)$$

• optimize over correlations  $p \in \{C, Q, Q_c\}$ 

# SOS relaxation over $\ensuremath{\mathcal{C}}$

$$\omega_{\mathcal{C}} = \sup_{p} \sum_{a,b,s,t} f_{abst} p_{s}^{a} \cdot p_{t}^{b}$$

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- We can write this as POP:
  - $f((\underline{p},\underline{q})) := \sum_{a,b,s,t} f_{abst} p_s^a \cdot q_t^b \in \mathbb{R}[\underline{p},\underline{q}]$
  - $\mathcal{K} = \{(\underline{p}, \underline{q}) \mid p_s^a, q_t^b \ge 0, \sum_a p_s^a = \sum_b q_t^b = 1\}$
  - M(g) is archimedean

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Hence

$$\begin{split} \omega_{\mathcal{C}} &= \sup f(\underline{p},\underline{q}); \quad \text{s.t.} \ (\underline{p},\underline{q}) \in K \\ &= \inf a \in \mathbb{R} \qquad \text{s.t.} \ a - f \geq 0 \text{ on } K \\ &= \inf a \in \mathbb{R} \qquad \text{s.t.} \ a - f \in M(g) \quad (f_{sos}) \\ &\leq \inf a \in \mathbb{R} \qquad \text{s.t.} \ a - f \in M(g)_t \quad (f_t) \end{split}$$

Converging hierarchy of SDP upper bounds

### SOS relaxation over $Q_c$

$$\omega_{\mathcal{Q}_{c}} = \sup \sum_{a,b,s,t} f_{abst} \psi^{\mathsf{T}} (\boldsymbol{E}_{s}^{a} \cdot \boldsymbol{F}_{t}^{b}) \psi$$

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Hence

$$\begin{split} \omega_{\mathcal{C}} &= \sup \psi^{\mathsf{T}} f(\underline{E}, \underline{F}) \psi; \quad \text{s.t.} \ (\underline{E}, \underline{F}) \in \mathsf{K} \\ &= \inf a \in \mathbb{R} \qquad \qquad \text{s.t.} \ a - f \succeq 0 \text{ on } \mathsf{K} \\ &= \inf a \in \mathbb{R} \qquad \qquad \text{s.t.} \ a - f \in \mathsf{M}_{\mathsf{nc}}(g) \quad (f_{\mathsf{sos}}) \\ &\leq \inf a \in \mathbb{R} \qquad \qquad \text{s.t.} \ a - f \in \mathsf{M}_{\mathsf{nc}}(g)_t \quad (f_t) \end{split}$$

#### Converging hierarchy of SDP upper bounds

#### SOS relaxation over Q

$$\omega_{\mathcal{Q}} = \sup \sum_{a,b,s,t} f_{abst} \operatorname{Tr}(E_s^a \otimes F_t^b)$$

► Cameron et al.: For most games we have  $p(a, b | s, t) = \text{Tr}(\tilde{E}_s^a \tilde{F}_t^b)$ with  $\tilde{E}_s^a, \tilde{F}_t^b \succeq 0, \sum_a \tilde{E}_s^a = \sum_b \tilde{F}_t^b = D$  with  $\text{Tr}(D^2) = 1$ 

#### SOS relaxation over $\mathcal{Q}$

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Hence

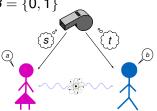
$$\begin{split} \omega_{\mathcal{C}} &= \sup \operatorname{Tr} f(\underline{E}, \underline{F}); \quad \text{s.t.} \ (\underline{E}, \underline{F}, D) \in K \\ &\leq \inf a \in \mathbb{R} \qquad \text{s.t.} \ a - f \in M_{tr}(g) \\ &\leq \inf a \in \mathbb{R} \qquad \text{s.t.} \ a - f \in M_{tr}(g)_t \end{split}$$

Converging sequence of upper SDP bounds

## **CHSH** Game

► Questions S = T = {0,1}, Answers A = B = {0,1}

Alice & Bob win, if  $a + b \equiv st \mod 2$ 



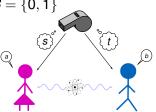
## **CHSH** Game

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$$\blacktriangleright \omega_{\mathcal{C}} = \frac{3}{4}$$

• 
$$\omega_{\mathcal{Q}} = \omega_{\mathcal{Q}_c} = \frac{1}{2} + \frac{1}{2\sqrt{2}} \approx 0.854$$

1<sup>st</sup> level of SOS hierarchies are exact



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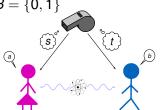
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- 1<sup>st</sup> level of SOS hierarchies are exact
- Alternative formulation:
- > 2 measurements with 2 outcomes each:  $E_s^0, E_s^1, F_t^0, F_t^1$
- Setting  $E_s := E_s^0 E_s^1$ ,  $F_t := F_t^0 F_t^1$  one obtains the CHSH inequality

$$f_{CHSH} := E_0 F_0 + E_0 F_1 + E_1 F_0 - E_1 F_1$$

• Optimizing  $f_{CHSH}$  over variants of C, Q give  $\omega_C, \omega_Q$ 



### I3322 inequality

• Questions  $S = T = \{0, 1, 2\}$ , Answers  $A = B = \{0, 1\}$ 

### $f := E_0F_0 + E_0F_1 + E_0F_2 + E_1F_0 + E_1F_1 - E_1F_3 + E_2F_0 - E_2F_1$ $- E_0 - 2F_0 - F_1$

## I3322 inequality

- ► Questions S = T = {0, 1, 2}, Answers A = B = {0, 1}
  - $f := E_0 F_0 + E_0 F_1 + E_0 F_2 + E_1 F_0 + E_1 F_1 E_1 F_3 + E_2 F_0 E_2 F_1$  $- E_0 - 2F_0 - F_1$
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- Maximizing over C:  $f_* \leq 0$
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- NC-SOS upper bounds:

level	psd	trace
1	0.375	0.375
2	0.25094006	0.2509397
3	0.25087556	0.2508754

► Pal & Vertesi computed (eigenvalue) SOS-bounds for 240 Bell inequalities of which 20 are not matching (≥ 10<sup>-4</sup>) the lower bound. 4 of them get exact (≤ 10<sup>-8</sup>) using trace SOS-bounds, about 1/2 of them improve





 $\chi(G) = \min t \in \mathbb{N} \text{ s.t. } x_u^i \in \{0, 1\}, u \in V(G), i \in [t],$  $\sum_{i \in [t]} x_u^i = 1 \quad \forall u \in V(G),$  $x_u^i x_u^j = 0 \quad \forall i \neq j, \forall u \in V(G),$  $x_u^i x_v^j = 0 \quad \forall uv \in E(G)$ 



 $\chi_q(G) = \min t \in \mathbb{N} \text{ s.t. } x_u^i \succeq 0, u \in V(G), i \in [t],$ 

$$\sum_{i \in [t]} x_u^i = 1 \quad \forall u \in V(G),$$
  

$$x_u^i x_u^j = 0 \quad \forall i \neq j, \forall u \in V(G), \quad (*)$$
  

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$$(x_u^i)^2 = x_u^i \quad \forall u \in V(G), i \in [t]$$

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We can write this as

min  $t \in \mathbb{N}$  s.t.  $\exists$  operator solution of (\*)

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### Nullstellensätze

Let  $g_1, \ldots, g_r \in \mathbb{C}[\underline{X}]$ 

Theorem (weak Nullstellensatz)

Let  $I = (g_1, \dots, g_r), V(I) := \{\underline{a} \in \mathbb{C}^n \mid g_1(\underline{a}) = \dots = g_r(\underline{a}) = 0\}.$  Then

 $V(I) = \emptyset \Leftrightarrow 1 \in I.$ 

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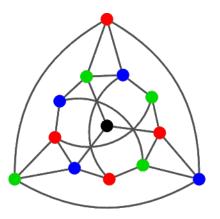
Let  $g_1, \ldots, g_r \in \mathbb{C}\langle \underline{X} \rangle$ 

Theorem (Amitsur Nullstellensatz) Let  $Z(I) := \{\underline{A} \in \mathbb{R}^n \mid \mathbb{R} \text{ primitive ring }, g_1(\underline{A}) = \cdots = g_r(\underline{A}) = 0\}$ . Then

 $Z(I) = \varnothing \Leftrightarrow 1 \in (g_1, \ldots, g_r).$ 

We have an algorithm to compute NC Gröbner bases, but it might not terminate...

## Against all odds...<sup>1</sup>

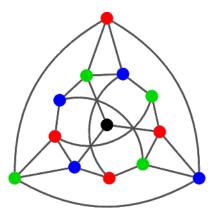


• Gröbner basis:  $4 \le \chi_q(G_{13})$ 

<sup>1</sup>with Piovesan, Mancinska, Roberson



## Against all odds...<sup>1</sup>



- Gröbner basis:  $4 \le \chi_q(G_{13}) \le \chi(G_{13}) = 4$
- Consequence  $\chi_q(G_{14}) = 4 < 5 = \chi(G_{14})$

<sup>&</sup>lt;sup>1</sup>with Piovesan, Mancinska, Roberson

## **Final Remarks**

- Quantum theory gives archimedean property for NC-SOS relaxations
- dual side (linear forms & moments) offers even more bounds (Laurent et al.)
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  - What is the geometry of (quantum) correlations?
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#### Thank you for your attention.

#### POEMA Polynomial Optimization, Efficiency through Moments and Algebra Marie Skłodowska-Curie Innovative Training Network 2019-2022



POEMA network goal is to train scientists at the interplay of algebra, geometry and computer science for polynomial optimization problems and to foster scientific and technological advances, stimulating interdisciplinary and intersectoriality knowledge exchange between algebraists, geometers, computer scientists and industrial actors facing real-life optimization problems.

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